

# A PROBABILISTIC APPROACH TO A THEOREM OF GILBARG AND SERRIN

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## ABSTRACT

We give a probabilistic proof via coupling of an extended version of a theorem of Gilbarg and Serrin.

## 1. Introduction

Let

$$L = \frac{1}{2} \sum_{i,j=1}^d a_{ij}(x) \frac{\partial^2}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i(x) \frac{\partial}{\partial x_i}$$

be defined on  $R^d$ ,  $d \geq 2$ . Except in the statement of Harnack's inequality below, we shall always assume that the coefficients satisfy:  $a_{ij} \in C^\alpha(R^d)$ ,  $b_i \in C^\alpha(R^d)$  and  $a(x) = \{a_{ij}(x)\}$  is positive definite for each  $x \in R^d$ . The main result of this paper will be proved under

ASSUMPTION A. (i)  $|b(x)| \leq M/(1 + |x|)$ , for all  $x \in R^d$ ;  
(ii)  $\lambda |\zeta|^2 \leq \sum_{i,j=1}^d a_{ij}(x) \zeta_i \zeta_j \leq \Lambda |\zeta|^2$ , for all  $x, \zeta \in R^d$ , where  $0 < \lambda \leq \Lambda < \infty$ .

We will give a probabilistic proof via coupling of the following Liouville-type result.

THEOREM 1. *Let  $L$  satisfy Assumption A.*

- (i) *If  $0 < u \in C^2(R^d)$  satisfies  $Lu = 0$  in  $R^d$ , then  $u = \text{constant}$ .*
- (ii) *Let  $D \subset R^d$  be an exterior domain. If  $0 < u \in C^2(D) \cap C(\bar{D})$  satisfies  $Lu = 0$  in  $D$ , then  $\lim_{|x| \rightarrow \infty} u(x)$  exists (but may be infinite).*

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In order to implement our coupling, we utilize the following version of Harnack's inequality proved in 1980 by Safanov ([7],[4]).

**HARNACK'S INEQUALITY.** Let

$$L = \frac{1}{2} \sum_{i,j=1}^d a_{ij}(x) \frac{\partial^2}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i(x) \frac{\partial}{\partial x_i}$$

be defined on a bounded domain  $\Omega \subset R^d$ . Assume that

$$\mu |\zeta|^2 \leq \sum_{i,j=1}^d a_{ij}(x) \zeta_i \zeta_j \leq \Lambda |\zeta|^2, \quad \text{for all } x \in \Omega \text{ and } \zeta \in R^d,$$

where  $0 < \lambda \leq \Lambda < \infty$ , and that  $\|b\|_\infty \equiv \sup_{x \in \Omega} |b(x)| < \infty$ . Let  $u \in W^{2,p}(\Omega)$  satisfy  $Lu = 0$  and  $u > 0$  in  $\Omega$ . Then for  $D \subset \bar{D} \subset \Omega$ ,  $\sup_D u \leq c \inf_D u$ , where  $c = c(\Lambda/\lambda, \|b\|_\infty/\lambda, D, \Omega)$ .

A nonprobabilistic proof of part (ii) of Theorem 1 (under the additional assumption that  $u$  satisfy a certain growth condition if  $d \geq 3$ ) was given in 1956 by Gilbarg and Serrin [3], who relied on Harnack's inequality. They used a version of Harnack's inequality proved by Serrin [8], which is weaker than Safanov's version. In particular, for  $d \geq 3$ , the constant  $c$  in Serrin's version depended on the modulus of continuity of  $a_{ij}$ . Consequently, Gilbarg and Serrin's theorem required that  $a_{ij}(x)$  possess a limit as  $|x| \rightarrow \infty$  in the case of  $R^d$ ,  $d \geq 3$ . They remarked that if Harnack's inequality were strengthened, then their result would be strengthened accordingly. Part (i) of Theorem 1 (under the additional condition that  $u$  be bounded if  $d \geq 3$ ) was stated without proof as a corollary to part (ii).

Before discussing our coupling technique, we investigate the connection between the statements in part (i) and part (ii) of Theorem 1 for general  $L$ , irrespective of Assumption A. Indeed, we feel that Theorem 2 below is of interest independent of the theorem we wish to prove. In the case that  $L$  generates a transient diffusion we have the following theorem.

**THEOREM 2.** *Assume that  $L$  generates a transient diffusion and let  $D$  be a smooth exterior domain. Then there are no nonconstant bounded  $C^2$ -solutions of  $Lu = 0$  in  $R^d$  if and only if for every bounded  $u \in C^2(D) \cap C(\bar{D})$  solving  $Lu = 0$  in  $D$  and for every sequence  $\{x_n\}_{n=1}^\infty$  such that  $\lim_{|n| \rightarrow \infty} |x_n| = \infty$  and  $\lim_{n \rightarrow \infty} P_{x_n}(\tau_D < \infty) = 0$ , the sequence  $\{u(x_n)\}_{n=1}^\infty$  tends to a limit which is independent of  $\{x_n\}_{n=1}^\infty$ . In particular, if  $\lim_{|x| \rightarrow \infty} P_x(\tau_D < \infty) = 0$ , then there are no nonconstant bounded  $C^2$ -solutions of  $Lu = 0$  in  $R^d$  if and only if every bounded solution  $u \in C^2(D) \cap C(\bar{D})$  of  $Lu = 0$  in  $D$  tends to a limit as  $|x| \rightarrow \infty$ .*

REMARK.  $v(x) \equiv P_x(\tau_D < \infty) \in C^2(R^d)$  and is the smallest positive solution of  $Lu = 0$  in  $D$  with  $u = 1$  on  $\partial D$ .

In the case that  $L$  generates a recurrent diffusion, we have the following well-known result.

PROPOSITION 1. *Let  $L$  generate a recurrent diffusion. If  $0 < u \in C^2(R^d)$  and  $Lu = 0$  in  $R^d$ , then  $u = \text{const.}$*

We now turn to our coupling technique. We introduce the following notation. Let  $\Omega = C([0, \infty), R^d)$  denote the space of continuous functions from  $[0, \infty)$  to  $R^d$  and let  $P_x$  denote the probability measure on  $\Omega$  corresponding to the diffusion generated by  $L$  and starting from  $x \in R^d$ . Denote trajectories in  $\Omega$  by  $X(\cdot)$ . Denote elements of the product space  $\Omega \times \Omega$  by  $(X(\cdot), Y(\cdot))$ . We distinguish between hitting times for  $X(\cdot)$  and  $Y(\cdot)$  by writing  $\tau_D(X(\cdot))$  and  $\tau_D(Y(\cdot))$ . For a probability measure  $Q$  on  $\Omega \times \Omega$ , let  $Q_i$  denote the  $i$ th marginal,  $i = 1, 2$ . The following coupling result holds irrespective of Assumption A. Similar types of results have been proven elsewhere; see for example [5] and [6].

THEOREM 3. (i) *Assume that for each  $(x, y) \in R^d \times R^d$  there exists a probability measure  $Q^{(x, y)}$  on  $\Omega \times \Omega$  such that*

- (1)  $Q_1^{(x, y)} = P_x$ ;
- (2)  $Q_2^{(x, y)} = P_y$ ;
- (3)  $Q^{(x, y)}((X(\cdot), Y(\cdot)) \in \Omega \times \Omega : \exists s_1 s_2 \geq 0 \text{ such that } X(s_1 + t) = Y(s_2 + t), \text{ for all } t \geq 0) = 1$ .

*Then every bounded solution  $u \in C^2(R^d)$  of  $Lu = 0$  in  $R^d$  is constant.*

(ii) *Let  $D \subset R^d$  be an exterior domain and let  $L$  generate a recurrent diffusion. Assume that for each  $\epsilon > 0$  there exists an  $n_\epsilon$  such that for each  $(x, y) \in R^d \times R^d$  with  $|x| \geq n_\epsilon$  and  $|y| \geq n_\epsilon$ , there exists a probability measure  $Q^{(x, y)}$  on  $\Omega \times \Omega$  satisfying*

- (1)  $Q_1^{(x, y)} = P_x$ ;
- (2)  $Q_2^{(x, y)} = P_y$ ;
- (3)  $Q^{(x, y)}(X(\tau_D(X(\cdot))) = Y(\tau_D(Y(\cdot)))) \geq 1 - \epsilon$ .

*Then  $\lim_{|x| \rightarrow \infty} u(x)$  exists for every bounded solution  $u \in C^2(D) \cap C(\bar{D})$  of  $Lu = 0$  in  $D$ .*

Under Assumption A, the coupling of Theorem 3 can be implemented. We have

THEOREM 4. *Let  $L$  satisfy Assumption A. Then*

- (i) *the coupling in (3)(i) may be achieved,*
- (ii) *the coupling in (3)(ii) may be achieved.*

The proof of Theorem 4 involves a scaling argument which can be used to give an easy proof of the following proposition.

**PROPOSITION 2.** *Let  $L$  satisfy Assumption A.*

- (i) *Let  $L$  generate a recurrent diffusion and let  $D$  be an exterior domain. Then  $v(x) = P_x(\tau_D < \infty)$  satisfies  $\lim_{|x| \rightarrow \infty} v(x) = 0$ .*
- (ii) *Let  $L$  generate a recurrent diffusion, let  $D$  be an exterior domain and let  $0 < u \in C^2(D) \cap C(\bar{D})$  satisfy  $Lu = 0$  in  $D$ . If  $u$  is unbounded, then  $\lim_{|x| \rightarrow \infty} u(x) = \infty$ .*
- (iii) *Let  $L$  generate a transient diffusion and let  $D$  be an exterior domain. If  $0 < u \in C^2(R^d)$  satisfies  $Lu = 0$  in  $R^d$  or if  $0 < u \in C^2(D)$  satisfies  $Lu = 0$  in  $D$ , then  $u$  is bounded.*

Theorem 1 now follows from Theorems 2, 3, and 4 and Propositions 1 and 2.

In Section 2 we will prove Theorems 2 and 3 and, for the sake of completeness, Proposition 1. The proofs of Theorem 4 and Proposition 2 are given in Section 3.

## 2. Proof of Proposition 1 and Theorems 2 and 3

**PROOF OF PROPOSITION 1.** Assume to the contrary that  $u$  is not constant. Then there exist bounded open sets  $D_1$  and  $D_2$  such that  $\sup_{x \in D_1} u(x) < \inf_{x \in D_2} u(x)$ . Let  $\tau_{D_2} = \inf\{t > 0 : X(t) \in D_2\}$  and  $\tau_n = \inf\{t > 0 : |X(t)| = n\}$ . Since  $Lu = 0$ ,  $u(X(t \wedge \tau_{D_2} \wedge \tau_n))$  is a  $P_x$ -martingale for each  $x \in R^d$ . Let  $x_0 \in D_1$ . Then  $u(x_0) = E_{x_0} u(X(t \wedge \tau_{D_2} \wedge \tau_n))$ . Letting  $t \rightarrow \infty$  gives  $u(x_0) = E_{x_0} u(X(\tau_{D_2} \wedge \tau_n))$ . By assumption,  $X(t)$  is a recurrent process so  $P_{x_0}(\tau_{D_2} < \infty) = 1$ . Thus letting  $n \rightarrow \infty$  and using the positivity of  $u$ , we obtain the contradiction  $u(x_0) \geq E_{x_0} u(X(\tau_{D_2})) \geq \inf_{x \in D_2} u(x)$ .

**PROOF OF THEOREM 2.** First assume that for every bounded solution  $u \in C^2(D) \cap C(\bar{D})$  of  $Lu = 0$  in the exterior domain  $D$  and for every sequence  $\{x_n\}_{n=1}^\infty$  such that  $\lim_{n \rightarrow \infty} |x_n| = \infty$  and  $\lim_{n \rightarrow \infty} P_{x_n}(\tau_D < \infty) = 0$ , the sequence  $\{u(x_n)\}_{n=1}^\infty$  tends to a limit which is independent of  $\{x_n\}_{n=1}^\infty$ . Let  $u \in C^2(R^d)$  be bounded and satisfy  $Lu = 0$  in  $R^d$ . We will prove that  $u$  is constant. Since  $u$  is also a solution of the exterior problem, it follows from our assumption that  $c \equiv \lim_{n \rightarrow \infty} u(x_n)$  exists for any sequence  $\{x_n\}_{n=1}^\infty$  such that  $\lim_{n \rightarrow \infty} |x_n| = \infty$  and  $\lim_{n \rightarrow \infty} P_{x_n}(\tau_D < \infty) = 0$ . Now  $v(x) = P_x(\tau_D < \infty)$  satisfies

$$\begin{aligned} \lim_{t \rightarrow \infty} v(X(t)) &= \lim_{t \rightarrow \infty} P_x(|X(s) \notin D \text{ for some } s \geq t | X(r), 0 \leq r \leq t) \\ &= 1_{\{|X(t_n) \notin D \text{ for some sequence } t_n \rightarrow \infty\}} \text{ a.s. } P_x \end{aligned}$$

(see [1, Theorem 9.5.1]). Thus, by transience,  $\lim_{t \rightarrow \infty} v(X(t)) = 0$  a.s.  $P_x$  and, consequently,  $\lim_{t \rightarrow \infty} u(X(t)) = c$  a.s.  $P_x$ . Since  $Lu = 0$ ,  $u(X(t))$  is a bounded  $P_x$ -martingale, and we obtain  $u(x) = E_x u(X(t)) = \lim_{t \rightarrow \infty} E_x u(X(t)) = c$ , for all  $x \in R^d$ . Thus  $u$  is constant.

Conversely, assume that every bounded solution  $u \in C^2(R^d)$  of  $Lu = 0$  in  $R^d$  is constant. Let  $\{x_n\}_{n=1}^\infty$  satisfy  $\lim_{n \rightarrow \infty} |x_n| = \infty$  and  $\lim_{n \rightarrow \infty} P_{x_n}(\tau_D < \infty) = 0$  and let  $u \in C^2(D) \cap C(D)$  be a bounded solution of  $Lu = 0$  in the exterior region  $D$ . We will show that  $u(x_n)$  possesses a limit at infinity and that the limit is independent of  $\{x_n\}_{n=1}^\infty$ . First extend  $u$  in an arbitrary manner so that it is defined on all of  $R^d$ . Define

$$\mathfrak{U}(X(\cdot)) = \begin{cases} \lim_{t \rightarrow \infty} u(X(t)) & \text{if the limit exists,} \\ 0 & \text{otherwise.} \end{cases}$$

Since  $Lu = 0$  in  $D$ ,  $u(X(t \wedge \tau_D))$  is a bounded  $P_x$ -martingale for  $x \in D$  and thus it converges a.s.  $P_x$  for  $x \in D$ . From this and the strong Markov property, it follows that  $|\mathfrak{U}| \leq \sup_{y \in D} |u(y)|$  a.s.  $P_x$  for  $x \in R^d$ . Clearly  $\mathfrak{U}$  is measurable with respect to the invariant  $\sigma$ -field and thus  $h(x) = E_x \mathfrak{U}$  is bounded and  $L$ -harmonic [2]. By our assumption, then,  $h(x) \equiv c$ . Now define

$$\mathfrak{V}(X(\cdot)) = \begin{cases} \lim_{t \rightarrow \infty} u(X(t \wedge \tau_D)) & \text{if the limit exists,} \\ 0 & \text{otherwise.} \end{cases}$$

Since  $u(X(t \wedge \tau_D))$  converges a.s.  $P_x$ , for  $x \in D$ ,  $|\mathfrak{V}| \leq \sup_{x \in D} |u(x)|$  a.s.  $P_x$  for  $x \in D$ . Furthermore,

$$(2.1) \quad u(x) = E_x \mathfrak{V} = E_x \mathfrak{V} \mathcal{G}_{(\tau_D=\infty)} + E_x \mathfrak{V} \mathcal{G}_{(\tau_D<\infty)}, \quad \text{for } x \in D.$$

But  $\mathfrak{V} \mathcal{G}_{(\tau_D=\infty)} = \mathfrak{U} \mathcal{G}_{(\tau_D=\infty)}$ . Thus, we have

$$c = h(x) = E_x \mathfrak{U} = E_x \mathfrak{V} \mathcal{G}_{\tau_D=\infty} + E_x \mathfrak{U} \mathcal{G}_{(\tau_D<\infty)}.$$

Plugging this into (2.1) gives

$$(2.2) \quad u(x) = c - E_x \mathfrak{U} \mathcal{G}_{(\tau_D<\infty)} + E_x \mathfrak{V} \mathcal{G}_{(\tau_D<\infty)}.$$

Since  $|\mathfrak{U}|$  and  $|\mathfrak{V}|$  are bounded by  $\sup_{x \in D} |u(x)|$  a.s.  $P_x$  for all  $x \in D$ , and since by assumption,  $\lim_{n \rightarrow \infty} P_{x_n}(\tau_D < \infty) = 0$ , it follows from (2.2) that  $\lim_{n \rightarrow \infty} u(x_n) = c$ . This completes the proof of the theorem.

We now turn to the

**PROOF OF THEOREM 3.** We will denote expectations with respect to  $P_x$  by  $E_x$  and expectations with respect to  $Q^{x,y}$  by  $E^{Q^{x,y}}$ .

*Part (i).* Let  $u \in C^2(R^d)$  be a bounded solution of  $Lu = 0$  in  $R^d$ . Then  $u(X(t))$  is a bounded  $P_x$ -martingale and thus converges a.s.  $P_x$ . By the same token, using the notation  $Y(\cdot)$  for paths in  $\Omega$ , it follows that  $u(Y(t))$  converges a.s.  $P_y$ . Thus, by properties (1) and (2) of  $Q^{(x,y)}$ , it follows that

$$(2.3) \quad (u(X(t)), u(Y(t))) \text{ converges as } t \rightarrow \infty \text{ a.s. } Q^{(x,y)},$$

$$(2.4) \quad u(x) = \lim_{t \rightarrow \infty} E_x u(X(t)) = \lim_{t \rightarrow \infty} E^{Q^{(x,y)}} u(X(t)),$$

$$(2.5) \quad u(y) = \lim_{t \rightarrow \infty} E_y u(Y(t)) = \lim_{t \rightarrow \infty} E^{Q^{(x,y)}} u(Y(t)).$$

From (2.3), (2.4) and (2.5) and property (3) of  $Q^{(x,y)}$ , we conclude that  $u(x) = u(y)$ . As  $x$  and  $y$  are arbitrary,  $u = \text{constant}$ .

*Part (ii).* Fix  $\epsilon > 0$  and let  $x, y \in D$  satisfy  $|x| > n_\epsilon$  and  $|y| > n_\epsilon$ . By properties (1) and (2) of  $Q^{(x,y)}$ , we have

$$\mu_x(dz) = P_x(X(\tau_D) \in dz) = Q^{(x,y)}(X(\tau_D(X(\cdot))) \in dz)$$

and

$$\mu_y(dz) = P_y(X(\tau_D) \in dz) = Q^{(x,y)}(Y(\tau_D(Y(\cdot))) \in dz).$$

Since  $Lu = 0$  in  $D$ ,  $u(X(t \wedge \tau_D))$  is a bounded  $P_x$ -martingale and thus  $u(x) = E_x u(X(t \wedge \tau_D))$ . Letting  $t \rightarrow \infty$  and using the boundedness of  $u$  and the recurrence of  $X(t)$  gives  $u(x) = E_x u(X(\tau_D)) = \int_{\partial D} u(z) \mu_x(dz)$ . Similarly,  $u(y) = \int_{\partial D} u(z) \mu_y(dz)$ . By property (3), it follows that

$$|u(x) - u(y)| = \left| \int_{\partial D} u(z) \mu_x(dz) - \int_{\partial D} u(z) \mu_y(dz) \right| \leq 2\epsilon \sup_{z \in \partial D} |u(z)|.$$

### 3. Proofs of Theorem 4 and Proposition 2

**PROOF OF THEOREM 4, part (i).** Let  $m = (\max(|x_0|, |y_0|) + \gamma)V/2$ , for some  $\gamma > 0$ . For  $X(\cdot) \in \Omega$ , define the following stopping times.

$$\sigma_0 = \sigma_0(X(\cdot)) = \inf\{t \geq 0 : |X(t)| = m\},$$

$$\sigma_j = \sigma_j(X(\cdot)) = \inf\{t > \sigma_{j-1} : |X(t)| = m^{j+1}\}, \quad j = 1, 2, \dots$$

It will also be convenient to define the following stopping times:

$$\tau_j = \tau_j(X(\cdot)) = \inf\{t \geq 0 : |X(t)| = m^{j+1}\}, \quad j = 0, 1, 2, \dots$$

Define  $\Sigma_j = \{|x| = m^{j+1}\}$ ,  $j = 0, 1, 2, \dots$ . For  $j = 0, 1, 2, \dots$  and  $|x| \leq m^{j+1}$ , define the harmonic measure  $\mu_x^j(dz) \in \mathcal{P}(\Sigma_j)$  by  $\mu_x^j(dz) = P_x(X(\tau_j) \in dz)$ .

Our coupling turns on the following

**CLAIM.** There exists a constant  $0 < c < 1$  and for each  $j = 0, 1, 2, \dots$  a probability measure  $\nu^j \in \mathcal{P}(\Sigma_j)$  such that

$$\mu_x^0(dz) \geq c\nu^0(dz), \quad \text{for } x = x_0 \text{ or } y_0$$

and

$$\mu_x^j(dz) \geq c\nu^j(dz), \quad \text{for } |x| = m^j, \quad j = 1, 2, \dots$$

We will now use this result to prove the theorem and then return to prove the Claim.

For  $(X(\cdot), Y(\cdot)) \in \Omega \times \Omega$ , we will let  $t$  denote the time variable in  $X(\cdot)$  and  $s$  denote the time variable in  $Y(\cdot)$ . Let  $X(t)$  and  $Y(s)$  run independently starting from  $x_0$  and  $y_0$ , respectively, up until time  $t = \sigma_0(X(\cdot))$  and  $s = \sigma_0(Y(\cdot))$ . That is, define  $Q$  on  $\mathfrak{F}_{\sigma_0(X(\cdot))} \times \mathfrak{F}_{\sigma_0(Y(\cdot))}$  by  $P_{x_0} \times P_{y_0}$ .

The distribution of  $X(\sigma_0(X(\cdot)))$  under  $Q$  or, equivalently, under  $P_{x_0}$ , and the distribution of  $Y(\sigma_0(Y(\cdot)))$  under  $Q$  or, equivalently, under  $P_{y_0}$ , are respectively  $\mu_{x_0}^0(dz)$  and  $\mu_{y_0}^0(dz)$ . By our Claim, we may write each of these as a convex combination of probability measures as follows:

$$\mu_{x_0}^0(dz) = c\nu^0(dz) + (1-c) \left[ \frac{(\mu_{x_0} - c\nu)(dz)}{1-c} \right],$$

$$\mu_{y_0}^0(dz) = c\nu^0(dz) + (1-c) \left[ \frac{(\mu_{y_0} - c\nu)(dz)}{1-c} \right].$$

We now describe how to continue the definition of  $Q$  starting from  $t = \sigma_0(X(\cdot))$  and  $s = \sigma_0(Y(\cdot))$ . With probability  $c$ , start both  $X(\cdot)$  and  $Y(\cdot)$  from the distribution  $\nu^0(dz)$  and couple them, that is, run them so that

$$X(\sigma_0(X(\cdot)) + r) = Y(\sigma_0(Y(\cdot)) + r) \quad \text{for all } r \geq 0$$

and so that  $X(\sigma_0(X(\cdot)) + \cdot) \sim P_{\nu^0}$ . With probability  $1 - c$ , let  $X(\cdot)$  and  $Y(\cdot)$  continue to run independently with  $X(\cdot)$  starting from  $X(\sigma_0(X(\cdot)))$  and  $Y(\cdot)$  starting from  $Y(\sigma_0(Y(\cdot)))$  with distributions

$$\frac{(\mu_{x_0} - c\nu)(dz)}{1 - c} \quad \text{and} \quad \frac{(\mu_{y_0} - c\nu)(dz)}{1 - c}$$

respectively. Use this recipe to continue the definition of  $Q$  from

$$\mathfrak{F}_{\sigma_0(X(\cdot))} \times \mathfrak{F}_{\sigma_0(Y(\cdot))} \quad \text{up to} \quad \mathfrak{F}_{\sigma_1(X(\cdot))} \times \mathfrak{F}_{\sigma_1(Y(\cdot))}.$$

To extend the definition of  $Q$  from

$$\mathfrak{F}_{\sigma_1(X(\cdot))} \times \mathfrak{F}_{\sigma_1(Y(\cdot))} \quad \text{up to} \quad \mathfrak{F}_{\sigma_2(X(\cdot))} \times \mathfrak{F}_{\sigma_2(Y(\cdot))}$$

we proceed as follows. By time  $t = \sigma_1(X(\cdot))$  and  $s = \sigma_1(Y(\cdot))$ ,  $X(\cdot)$  and  $Y(\cdot)$  are already coupled with probability  $c$ ; continue to run them coupled. With probability  $1 - c$ ,  $X(\cdot)$  and  $Y(\cdot)$  are still running independently at time  $t = \sigma_1(X(\cdot))$  and  $s = \sigma_1(Y(\cdot))$ . Now the distributions of  $X(\sigma_1(X(\cdot)))$  and  $Y(\sigma_1(Y(\cdot)))$ , given that they are still running independently, are respectively

$$\hat{\mu}_{x_0}^1(dz) \equiv \int_{\Sigma_0} \mu_y^1(dz) \frac{(\mu_{x_0} - c\nu)(dy)}{1 - c}$$

and

$$\hat{\mu}_{y_0}^1(dz) \equiv \int_{\Sigma_0} \mu_y^1(dz) \frac{(\mu_{y_0} - c\nu)(dy)}{1 - c}.$$

By the Claim,  $\mu_y^1(dz) \geq c\nu^1(dz)$ , for all  $y \in \Sigma_0$ . Thus we may write  $\hat{\mu}_{x_0}^1$  and  $\hat{\mu}_{y_0}^1$  as convex combinations of probability distributions as follows:

$$\begin{aligned} \hat{\mu}_{x_0}^1(dz) &= c\nu^1(dz) + (1 - c) \left[ \frac{(\hat{\mu}_{x_0}^1 - c\nu^1)(dz)}{1 - c} \right], \\ \hat{\mu}_{y_0}^1(dz) &= c\nu^1(dz) + (1 - c) \left[ \frac{(\hat{\mu}_{y_0}^1 - c\nu^1)(dz)}{1 - c} \right]. \end{aligned}$$

Thus, as before, with probability  $c$  we couple and with probability  $1 - c$  we allow the paths to continue independently up till time  $t = \sigma_2(X(\cdot))$  and  $s = \sigma_2(Y(\cdot))$ . Continuing inductively, by time  $t = \sigma^k(X(\cdot))$  and  $s = \sigma^k(Y(\cdot))$ , the probability that paths are coupled is  $\sum_{j=0}^k c(1 - c)^j$  and as  $k \rightarrow \infty$ , this probability converges to one. Clearly, the three properties of Theorem 3(i) are met.

We now prove the Claim for  $j \geq 1$ . The same argument works for  $j = 0$  but the notation must be altered to accommodate this case. Fix  $j \geq 1$  and consider  $X(t)$ ,  $0 \leq t \leq \tau_j$  under  $P_x|_{\mathfrak{F}_{\sigma_j}^j}$  with  $|x| = m^j$ . Scale the process by a factor of  $1/m^j$ . The new generator is  $(1/m^{2j})\hat{L}_j$ , where



$$\hat{L}_j = \frac{1}{2} \sum_{i,k=1}^d a_{ik}^{(j)}(x) \frac{\partial^2}{\partial x_i \partial x_k} + \sum_{i=1}^d b_i^{(j)}(x) \frac{\partial}{\partial x_i},$$

$$a^{(j)}(x) = a(m^j x) \quad \text{and} \quad b^{(j)}(x) = m^j b(m^j x).$$

If we let  $\hat{P}_z^j$  denote the probability measure on  $C([0, \infty), R^d)$  corresponding to the generator  $(1/m^{2j})\hat{L}_j$  and starting from  $z \in R^d$ , then the measure induced by  $P_x|_{\mathcal{F}_{0^j}}$  under the scaling is  $(\hat{P}_{x/m^j}^j)|_{\mathcal{F}_{\tau_0}}$ . Let  $\hat{\mu}_y^j(dz) = \hat{P}_y^j(X(\tau_0) \in dz)$ , for  $|y| \leq m$ . With a slight abuse of notation, let  $\mu_x^j(d\phi)$  and  $\hat{\mu}_y^j(d\phi)$  denote the marginal distributions of  $\mu_x^j(dz)$  and  $\hat{\mu}_y^j(dz)$  on  $S^{d-1}$ . Then, clearly,

$$\hat{\mu}_{x/m^j}^j(d\phi) = \mu_x^j(d\phi), \quad \text{for } |x| \leq m^{j+1}.$$

Thus to prove the Claim, it suffices to find a  $\nu^j(d\phi) \in \mathcal{P}(S^{d-1})$  and  $c > 0$  such that  $\hat{\mu}_y^j(d\phi) > c\nu^j(d\phi)$ , for all  $j = 1, 2, \dots$  and  $|y| = 1$ . We will show that there exists a  $c > 0$  such that for any fixed  $y_0$  with  $|y_0| = 1$ ,

$$(3.1) \quad \hat{\mu}_y^j(d\phi) \geq c\hat{\mu}_{y_0}^j(d\phi), \quad \text{for } j = 1, 2, \dots \quad \text{and} \quad |y| = 1,$$

and thus we map pick  $\nu^j(d\phi) = \hat{\mu}_{y_0}^j(d\phi)$ .

To prove (3.1), it is enough to show that for all nonnegative  $f \in C^\infty(S^{d-1})$ , all  $j = 1, 2, \dots$  and all  $|y| = 1$ ,

$$\int_{S^{d-1}} f(\phi) \hat{\mu}_y^j(d\phi) \geq c \int_{S^{d-1}} f(\phi) \hat{\mu}_{y_0}^j(d\phi),$$

for some  $0 < c < 1$ . Let

$$u_j(y) = \int_{S^{d-1}} f(\phi) \hat{\mu}_y^j(d\phi), \quad \text{for } |y| \leq m.$$

By the smoothness assumptions on  $a_{ij}$  and  $b_i$ , there exists a solution  $v_j \in C^{2,\alpha}$  of  $\hat{L}_j v_j = 0$  in  $|y| < m$  with  $v_j = f$  on  $|y| = m$  [4]. In fact, then,  $v_j = u_j$ . Now consider the domains  $D = \{\frac{3}{4} < |x| < \frac{3}{2}\}$  and  $\Omega = \{\frac{1}{2} < |x| < m\}$ . The diffusion matrix  $a^j(x)$  satisfies Assumption A(ii) for  $x \in \Omega$ . By Assumption A(i),

$$\sup_j \sup_{x \in \Omega} |b^{(j)}(x)| \leq \sup_j \sup_{x \in \Omega} \frac{m^j M}{1 + |xm^j|} \leq 2M.$$

Thus, by Harnack's inequality, there exists a  $0 < c < 1$  such that

$$u_j(y) > cu_j(y_0) \quad \text{for all } j = 1, 2, \dots \quad \text{and} \quad y \in D.$$

This completes the proof of the Claim.

PROOF OF THEOREM 4, *part (ii)*. As the proof is very similar to that of part (i), we just give a sketch of the proof.

Fix  $m$  such that  $D^c \subset \{|x| < m\}$ . Now fix  $(x_0, y_0) \in R^d \times R^d$  with  $|x_0|, |y_0| \geq m$  and, without loss of generality, assume that  $|x_0| \leq |y_0|$ . Let  $j_0$  be the positive integer satisfying  $m^{j_0} \leq |x_0| < m^{j_0+1}$ .

Let

$$\begin{aligned}\sigma_{j_0} &= \sigma_{j_0}(X(\cdot)) = \inf\{t \geq 0 : |X(t)| = m^{j_0}\}, \\ \sigma_j &= \sigma_j(X(\cdot)) = \inf\{t > \sigma_{j+1} : |X(t)| = m^j\}, \quad j = j_0 - 1, j_0 - 2, \dots, 1.\end{aligned}$$

Also let

$$\tau_j = \tau_j(X(\cdot)) = \inf\{t \geq 0 : |X(t)| = m^j\}, \quad j = 1, 2, \dots,$$

and define

$$\Sigma_j = \{|x| = m^j\}, \quad j = 1, 2, \dots$$

For  $j = 1, 2, \dots, j_0$ , and  $|x| \geq m^j$ , define the harmonic measure  $\mu_x^j(dy) \in \mathcal{P}(\Sigma_j)$  by  $\mu_x^j(dy) = P_x(X(\tau_j) \in dy)$ . The same proof as in part (i) shows that there exists a  $c > 0$ , independent of  $j_0$ , and for each  $j = 1, 2, \dots, j_0 - 1$ , a measure  $\nu^j(dy) \in \mathcal{P}(\Sigma_j)$  such that

$$(3.2) \quad \mu_x^j(dy) \geq c\nu^j(dz), \quad \text{for } |x| = m^{j+1} \quad \text{and } j = 1, 2, \dots, j_0 - 1.$$

Now run  $X(t)$  and  $Y(s)$  independently, as in part (i), starting from  $x_0$  and  $y_0$  respectively up until  $t = \sigma_{j_0-1}(X(\cdot))$  and  $s = \sigma_{j_0-1}(Y(\cdot))$ . By invoking the strong Markov property at  $\sigma_{j_0}(X(\cdot))$  and  $\sigma_{j_0}(Y(\cdot))$  and using (3.2), it follows that we may couple  $X(\cdot)$  and  $Y(\cdot)$  after time  $t = \sigma_{j_0-1}(X(\cdot))$  and  $s = \sigma_{j_0-1}(Y(\cdot))$  with probability  $c$ . Continuing as in part (i), we find that by time  $t = \sigma_1(X(\cdot))$  and  $s = \sigma_1(Y(\cdot))$ , the probability that  $X(\cdot)$  and  $Y(\cdot)$  are coupled is  $\sum_{j=0}^{j_0-2} c(1-c)^j$ . Thus property 3 of Theorem 2, part (ii), is satisfied with  $\epsilon = \sum_{j=j_0-1}^{\infty} c(1-c)^j$  and  $n = m^{j_0}$ .

PROOF OF PROPOSITION 2, *part (i)*. Since  $Lv = 0$  in  $D$ ,  $v(X(t \wedge \tau_D))$  is a martingale. By the martingale convergence theorem [1],  $\lim_{t \rightarrow \infty} v(X(t \wedge \tau_D)) = I_{\tau_D < \infty}(X(\cdot))$  a.s.  $P_x$ . Since the process is transient, it follows that there exists an  $X_0(\cdot) \in \Omega$  such that  $\lim_{t \rightarrow \infty} |X_0(t)| = \infty$  and

$$(3.3) \quad \lim_{t \rightarrow \infty} v(X_0(t)) = 0.$$

Now assume that Proposition 2(i) is false. Then there exists an  $\epsilon > 0$  and a sequence  $\{x_n\}_{n=1}^\infty$  with  $\lim_{n \rightarrow \infty} |x_n| = \infty$  such that  $v(x_n) > \epsilon$  for all  $n$ . By (3.3) we may find a sequence  $\{y_n\}_{n=1}^\infty$  such that  $|y_n| = |x_n|$  and

$$(3.4) \quad \lim_{n \rightarrow \infty} v(y_n) = 0.$$

Let  $m_n = |x_n| = |y_n|$  and scale space by a factor of  $m_n$ . That is, let  $v_n(x) = v(m_n x)$ ,  $a^{(n)}(x) = a(m_n x)$ ,  $b^{(n)}(x) = m_n b(m_n x)$ , and

$$\hat{L}_n = \sum_{i,j=1}^d a_{ij}^{(n)} \frac{\partial^2}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i^{(n)} \frac{\partial}{\partial x_i}.$$

As in the proof of Theorem 4, it follows that  $\hat{L}_n v_n = 0$  in  $R^d$  and that by Harnack's inequality, there exists a  $c > 0$  independent of  $n$  such that

$$(3.5) \quad \sup_{|x|=1} v_n(x) \leq c \inf_{|x|=1} v_n(x).$$

But

$$v_n\left(\frac{x_n}{m_n}\right) = v(x_n) > \epsilon \quad \text{and} \quad v_n\left(\frac{y_n}{m_n}\right) = v(y_n) \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

This contradicts (3.5).

*Part (ii).* In part (i) we showed by scaling and Harnack's inequality that if  $\lim_{n \rightarrow \infty} v(y_n) = 0$ , then in fact  $\lim_{|x| \rightarrow \infty} v(x) = 0$ . In the present case, the same technique shows that if  $\lim_{n \rightarrow \infty} u(x_n) = \infty$  for some sequence  $\{x_n\}_{n=1}^\infty$  satisfying  $\lim_{n \rightarrow \infty} |x_n| = \infty$ , then  $\lim_{|x| \rightarrow \infty} u(x) = \infty$ .

*Part (iii).* Assume to the contrary that  $u$  is unbounded. Then the technique of parts (i) and (ii) shows that in fact  $\lim_{|x| \rightarrow \infty} u(x) = \infty$ . Consider first the case that  $u$  satisfies  $Lu = 0$  in  $R^d$ . Then for each  $x \in R^d$ ,  $u(X(t \wedge \tau_n))$  is a  $P_x$ -martingale, where  $\tau_n = \inf\{t \geq 0: |X(t)| = n\}$ . Letting  $t \rightarrow \infty$ , we have  $u(x) = E_x u(X(\tau_n)) \geq \inf_{|y|=n} u(y)$ , and letting  $n \rightarrow \infty$  gives  $u(x) \equiv \infty$ . Now consider the case  $Lu = 0$  in  $D$ . Then for each  $x \in D$ ,  $u(X(t \wedge \tau_D \wedge \tau_n))$  is a  $P_x$ -martingale. Letting  $t \rightarrow \infty$  gives

$$u(x) = E_x(X(\tau_D \wedge \tau_n)) \geq \inf_{|y|=n} u(y) P_x(\tau_D > \tau_n).$$

By the transience assumption,  $\lim_{n \rightarrow \infty} P_x(\tau_D > \tau_n) > 0$ . Thus, letting  $n \rightarrow \infty$  again gives  $u(x) \equiv \infty$ .

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